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# Stability of 1-dimensional stationary solution to the compressible Navier-Stokes equations on the half space

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## 1. Introduction

This article is concerned with the compressible Navier-Stokes equation on the half space  $\mathbf{R}_+^n$  ( $n \geq 2$ ) :

$$(1.1) \quad \begin{aligned} \partial_t \rho + \operatorname{div}(\rho u) &= 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla p(\rho) &= \mu \Delta u + (\mu + \mu') \nabla \operatorname{div} u, \\ p(\rho) &= K \rho^\gamma. \end{aligned}$$

Here  $\mathbf{R}_+^n = \{x = (x_1, x'); x' = (x_2, \dots, x_n) \in \mathbf{R}^{n-1}, x_1 > 0\}$ ;  $\rho = \rho(x, t)$  and  $u = (u^1(x, t), \dots, u^n(x, t))$  denote the unknown density and velocity, respectively;  $\mu, \mu', K$  and  $\gamma$  are constants satisfying  $\mu > 0, \frac{2}{n}\mu + \mu' \geq 0, K > 0$  and  $\gamma > 1$ . We consider (1.1) under the initial and boundary conditions

$$(1.2) \quad \begin{aligned} u|_{x_1=0} &= (u_b^1, 0, \dots, 0), \\ \rho \rightarrow \rho_+, \quad u &\rightarrow (u_+^1, 0, \dots, 0) \quad (x_1 \rightarrow \infty), \\ (\rho, u)|_{t=0} &= (\rho_0, u_0), \end{aligned}$$

where  $\rho_+, u_+^1$  and  $u_b^1$  are given constants satisfying  $\rho_+ > 0$  and  $u_b^1 < 0$ .

Kawashima, Nishibata and Zhu [4] investigated the conditions for  $\rho_+, u_+^1$  and  $u_b^1$  under which planar stationary motions occur. Namely, they showed that under suitable conditions for  $\rho_+, u_+^1$  and  $u_b^1$  there exists a stationary solution  $(\tilde{\rho}, \tilde{u})$  of problem (1.1)–(1.2) in the form  $\tilde{\rho} = \tilde{\rho}(x_1), \tilde{u} = (\tilde{u}^1(x_1), 0, \dots, 0)$ . Furthermore, it was shown in [4] that  $(\tilde{\rho}, \tilde{u})$  is asymptotically stable with respect to small one-dimensional perturbations, i.e.,

perturbations in the form  $\rho - \tilde{\rho} = \rho(x_1, t) - \tilde{\rho}(x_1)$ ,  $u - \tilde{u} = (u^1(x_1, t) - \tilde{u}^1(x_1), 0, \dots, 0)$ , provided that  $|u_+^1 - u_b^1|$  is sufficiently small.

In this article we will give a summary of the results in [3], where  $(\tilde{\rho}, \tilde{u})$  is shown to be asymptotically stable with respect to multi-dimensional perturbations small in  $H^s(\mathbf{R}_+^n)$ , provided that  $|u_+^1 - u_b^1|$  is sufficiently small. Here  $s$  is an integer satisfying  $s \geq [n/2] + 1$ .

## 2. Stability Result

We first consider the one-dimensional stationary problem whose solutions represent planar stationary motions in  $\mathbf{R}_+^n$ . We look for a smooth stationary solution  $(\tilde{\rho}, \tilde{u})$  of (1.1)–(1.2) of the form  $\tilde{\rho} = \tilde{\rho}(x_1) > 0$  and  $\tilde{u} = (\tilde{u}^1(x_1), 0, \dots, 0)$ . Then the problem for  $(\tilde{\rho}, \tilde{u}^1)$  is written as

$$(2.1) \quad \begin{aligned} (\tilde{\rho} \tilde{u}^1)_{x_1} &= 0 \quad (x_1 > 0), \\ (\tilde{\rho} (\tilde{u}^1)^2)_{x_1} + p(\tilde{\rho})_{x_1} &= (2\mu + \mu') \tilde{u}_{x_1 x_1}^1 \quad (x_1 > 0), \\ \tilde{u}|_{x_1=0} &= u_b^1, \\ \tilde{\rho} &\rightarrow \rho_+, \quad \tilde{u}^1 \rightarrow u_+^1 \quad (x_1 \rightarrow \infty), \end{aligned}$$

where subscript  $x_1$  stands for differentiation in  $x_1$ .

Kawashima, Nishibata and Zhu [4] investigated problem (2.1) and gave a necessary and sufficient condition for the existence of solutions. Following [4], we introduce the Mach number at infinity defined by

$$M_+ \equiv \frac{|u_+|}{\sqrt{p'(\rho_+)}}.$$

We also set

$$\delta \equiv |u_+^1 - u_b^1|,$$

which measures the strength of the stationary solution.

**Proposition 2.1.** ([4]) *Let  $u_+^1 < 0$ . Then problem (2.1) has a smooth solution  $(\tilde{\rho}, \tilde{u}^1)$  if and only if  $M_+ \geq 1$  and  $w_c u_+ > u_b$ , where  $w_c$  is a certain positive number. The solution  $(\tilde{\rho}, \tilde{u}^1)$  is monotonic, in particular,  $\tilde{u}^1(x_1)$  is monotonically increasing when  $M_+ = 1$ . Furthermore,  $(\tilde{\rho}, \tilde{u}^1)$  has the following decay properties as  $x_1 \rightarrow \infty$ .*

(i) *If  $M_+ > 1$ , then for any nonnegative integer  $k$  there exists a constant  $C > 0$  such that*

$$|\partial_{x_1}^k (\tilde{\rho} - \rho_+, \tilde{u}^1 - u_+^1)| \leq C \delta e^{-\sigma x_1}$$

*for some positive constant  $\sigma$ .*

(ii) If  $M_+ = 1$ , then for any nonnegative integer  $k$  there exists a constant  $C > 0$  such that

$$|\partial_{x_1}^k(\tilde{\rho} - \rho_+, \tilde{u}^1 - u_+^1)| \leq C \frac{\delta^{k+1}}{(1 + \delta x_1)^{k+1}}.$$

Our interest is the stability properties of  $(\tilde{\rho}, \tilde{u})$ ,  $\tilde{u} = (\tilde{u}^1, 0, \dots, 0)$ , with respect to multi-dimensional perturbations. To state our stability result we introduce function spaces. For  $0 < T \leq \infty$  and  $\sigma \in \mathbf{Z}$ ,  $\sigma \geq 0$ , we define the Banach space

$$Z^\sigma(T) = X^\sigma(T) \times Y^\sigma(T)^n,$$

where

$$X^\sigma(T) = \bigcap_{j=0}^{[\frac{\sigma}{2}]} C^j([0, T]; H^{\sigma-2j})$$

and

$$Y^\sigma(T) = X^\sigma(T) \cap \bigcap_{j=0}^{[\frac{\sigma+1}{2}]} H^j(0, T; \tilde{H}^{\sigma+1-2j}).$$

Here  $\tilde{H}^m = H^m \cap H_0^1$  when  $m \geq 1$  and  $\tilde{H}^m = L^2$  when  $m = 0$ . The norm of  $Z^\sigma(T)$  is defined by  $\|U\|_{Z^\sigma(T)} = \|\phi\|_{X^\sigma(T)} + \|\psi\|_{Y^\sigma(T)}$  for  $U = (\phi, \psi)$ , where

$$\|\phi\|_{X^\sigma(T)} = \sup_{0 \leq t \leq T} |[\phi(t)]|_\sigma, \quad \|\psi\|_{Y^\sigma(T)} = \left( \|\psi\|_{X^\sigma(T)}^2 + \int_0^T |[\psi(t)]|_{\sigma+1}^2 dt \right)^{1/2}$$

with

$$|[\phi(t)]|_{\sigma,k} = \left( \sum_{j=0}^k \|\partial_t^j \phi(t)\|_{H^{\sigma-2j}}^2 \right)^{1/2}, \quad |[\phi(t)]|_\sigma = |[\phi(t)]|_{\sigma, [\frac{\sigma}{2}]}.$$

We simply denote by  $Z^\sigma$ ,  $X^\sigma$  and  $Y^\sigma$  when  $T = \infty$ .

**Theorem 2.2.** *Let  $s$  be an integer satisfying  $s \geq [n/2] + 1$  and let  $(\tilde{\rho}, \tilde{u})$  be the solution of (2.1). Then there exists a positive number  $\delta_0$  such that if  $|u_b^1 - u_+^1| < \delta_0$ , then  $(\tilde{\rho}, \tilde{u})$  is stable with respect to perturbations small in  $H^s(\mathbf{R}_+^n)$  in the following sense: there exist  $\varepsilon_0 > 0$  and  $C > 0$  such that if the initial perturbation  $(\rho(0) - \tilde{\rho}, u(0) - \tilde{u}) \in H^s$  and satisfies a suitable compatibility condition, then perturbation  $(\rho(t) - \tilde{\rho}, u(t) - \tilde{u})$  exists in  $Z^s$ , and it satisfies*

$$\|(\rho(t) - \tilde{\rho}, u(t) - \tilde{u})\|_{H^s} \leq C \|(\rho(0) - \tilde{\rho}, u(0) - \tilde{u})\|_{H^s}$$

for all  $t \geq 0$  and

$$\lim_{t \rightarrow \infty} \|\partial_x(\rho(t) - \tilde{\rho}, u(t) - \tilde{u})\|_{H^{s-1}} = 0,$$

provided that  $\|(\rho(0) - \tilde{\rho}, u(0) - \tilde{u})\|_{H^s} \leq \varepsilon_0$ . In particular,

$$\lim_{t \rightarrow \infty} \|(\rho(t) - \tilde{\rho}, u(t) - \tilde{u})\|_{\infty} = 0.$$

**Remarks.** (i) The stability of  $(\tilde{\rho}, \tilde{u})$  was firstly investigated in [4] and they proved Theorem 2.1 for  $n = 1$ , i.e.,  $(\tilde{\rho}, \tilde{u})$  is stable with respect to small perturbations in the form  $\rho - \tilde{\rho} = \rho(x_1, t) - \tilde{\rho}(x_1)$ ,  $u - \tilde{u} = (u^1(x_1, t) - \tilde{u}^1(x_1), 0, \dots, 0)$ .

(ii) We here consider large time behavior of solutions of (1.1)–(1.2) only under the conditions for  $\rho_+$ ,  $u_b^1$  and  $u_+^1$  given in Proposition 2.1. As is easily imagined, if one of these conditions would be disturbed, then complicated phenomena might occur. In fact, Matsumura [5] proposed a classification of all possible time asymptotic states in terms of boundary data for one-dimensional problem. Some parts of this classification were already proved rigorously. See [5].

### 3. Outline of the Proof

Let us rewrite the problem into the one for perturbations. We set  $(\phi, \psi) = (\rho - \tilde{\rho}, u - \tilde{u})$ . Then problem (1.1)–(1.2) is transformed into

$$\begin{aligned} (3.1) \quad & \partial_t \phi + u \cdot \nabla \phi + \rho \operatorname{div} \psi = F, \\ & \rho(\partial_t \psi + u \cdot \nabla \psi) + L\psi + p'(\rho) \nabla \phi = G, \\ & \psi|_{x_1=0} = 0; \quad (\phi, \psi) \rightarrow (0, 0) \quad (x_1 \rightarrow \infty), \\ & (\phi, \psi)|_{t=0} = (\phi_0, \psi_0) \end{aligned}$$

where

$$\begin{aligned} L\psi &= -\mu \Delta \psi - (\mu + \mu') \nabla \operatorname{div} \psi, \\ F &= -\psi \cdot \nabla \tilde{\rho} - \phi \operatorname{div} \tilde{u}, \\ G &= -(\rho \psi + \phi \tilde{u}) \cdot \nabla \tilde{u} - (p'(\rho) - p'(\tilde{\rho})) \nabla \tilde{\rho}. \end{aligned}$$

The proof of Theorem 2.1 is thus reduced to showing the global existence of solution  $(\phi, \psi)$  of (3.1) in the class  $Z^s$ , where  $s$  is an integer satisfying  $s \geq [n/2] + 1$ .

Let us firstly consider the local existence of solutions. The local existence can be proved by applying the result in [2]. In fact, problem (3.1) is a hyperbolic-parabolic system satisfying the assumptions in [2] that guarantees the local solvability in  $H^s$  for  $s$  satisfying  $s \geq [n/2] + 1$ . Therefore, we obtain the following

**Proposition 3.1.** *Let  $s$  be an integer satisfying  $s \geq s_0 = [\frac{n}{2}] + 1$ . Assume that the initial value  $(\phi_0, \psi_0)$  satisfies the following conditions.*

- (a)  $(\phi_0, \psi_0) \in H^s$  and  $(\phi_0, \psi_0)$  satisfies the  $\widehat{s}$ -th order compatibility condition, where  $\widehat{s} = [\frac{s-1}{2}]$ .
- (b)  $\inf_x \rho_0(x) \geq -\frac{1}{4} \inf_{x_1} \widetilde{\rho}(x_1)$ .

Then there exists a positive number  $T_0$  depending on  $\|(\phi_0, \psi_0)\|_{H^s}$  and  $\inf_{x_1} \widetilde{\rho}(x_1)$  such that problem (3.1) has a unique solution  $(\phi, \psi) \in Z^s(T_0)$  satisfying  $\phi(x, t) \geq -\frac{1}{2} \inf_{x_1} \widetilde{\rho}(x_1)$  for all  $(x, t) \in \mathbf{R}_+^n \times [0, T_0]$ . Furthermore, there exist constants  $C > 0$  and  $\gamma > 0$  depending on  $s$ ,  $\|(\phi_0, \psi_0)\|_{H^s}$  and  $\inf_{x_1} \widetilde{\rho}(x_1)$  such that

$$\|(\phi, \psi)\|_{Z^s(T_0)}^2 \leq C \{1 + \|(\phi_0, \psi_0)\|_{H^s}^2\}^\gamma \|(\phi_0, \psi_0)\|_{H^s}^2.$$

We next derive a priori estimates to show the global existence of solution. We define  $E_\sigma(t)$  and  $D_\sigma(t)$  by

$$E_\sigma(t) = \left( \sup_{0 \leq \tau \leq t} \{ \|\psi(\tau)\|_\sigma^2 + \|\phi(\tau)\|_{H^\sigma}^2 + \|[\partial_\tau \phi(\tau)]\|_{\sigma-1}^2 \} \right)^{1/2}$$

and

$$D_\sigma(t) = \begin{cases} \left( \int_0^t \|\partial_x \psi\|_2^2 + \|\phi|_{x_1=0}\|_{L^2(\mathbf{R}^{n-1})}^2 d\tau \right)^{1/2} & \text{for } \sigma = 0, \\ \left( \int_0^t \|\partial_x \psi\|_{H^\sigma}^2 + \|\phi|_{x_1=0}\|_{L^2(\mathbf{R}^{n-1})}^2 \right. \\ \quad \left. + \|\partial_x \phi\|_{H^{\sigma-1}}^2 + \|[\partial_\tau \phi]\|_{\sigma-1}^2 + \|[\partial_\tau \psi]\|_{\sigma-1}^2 d\tau \right)^{1/2} & \text{for } \sigma \geq 1. \end{cases}$$

In what follows we will denote the solution  $(\phi, \psi)$  and the initial value  $(\phi_0, \psi_0)$  by

$$U = (\phi, \psi), \quad U_0 = (\phi_0, \psi_0).$$

Theorem 2.2 follows from Proposition 3.1 and the following a priori estimate.

**Proposition 3.2.** *Let  $U = (\phi, \psi)$  be a solution of (3.1) on  $[0, T]$ . Assume that  $E_s(t) < 1$  for all  $t \in [0, T]$ . Then there exist constants  $\varepsilon_0 > 0$  and  $C > 0$ , which are independent of  $T > 0$ , such that*

$$E_s(t)^2 + D_s(t)^2 \leq C \|U_0\|_{H^s}^2$$

for all  $t \in [0, T]$ , provided that  $\|U_0\|_{H^s} < \varepsilon_0$ .

### Outline of the proof of Proposition 3.2

As in the one-dimensional problem studied in [4], the point in the proof of Proposition 3.2 is to derive a suitable bound for the  $L^2$  norm of  $(\phi, \psi)$ . Due to the fact that the stationary solution has no shear components, one can obtain the  $L^2$  bound in the same way as in the one-dimensional case in [4].

**Proposition 3.3.** *There exists a constant  $M > 0$  such that if*

$$(3.2) \quad E_s(t) \leq M$$

for all  $t \in [0, T]$ , then

$$E_0(t)^2 + D_0(t)^2 \leq C \{\|U_0\|_2^2 + R_0(t)^2\},$$

uniformly in  $t \in [0, T]$ , where  $C > 0$  is independent of  $T$  and

$$R_0(t)^2 = - \int_0^t \left\{ (\rho\psi \cdot \nabla \tilde{u}, \psi) + ((p(\rho) - p(\tilde{\rho}) - p'(\rho))\phi, \operatorname{div} \tilde{u}) + \left(\frac{1}{\rho}\phi L\tilde{u}, \psi\right) \right\} d\tau.$$

**Proof.** As in [4], we introduce an energy functional based on the energy function defined by

$$\rho\mathcal{E} = \rho\left\{\frac{1}{2}|u|^2 + \Phi(\rho)\right\}, \quad \Phi(\rho) = \int^\rho \frac{p(\zeta)}{\zeta^2} d\zeta.$$

Note that  $\Phi(\rho)$  is a strictly convex function of  $\frac{1}{\rho}$ . We then define

$$\rho\tilde{\mathcal{E}} = \rho\left\{\frac{1}{2}|\psi|^2 + \Psi(\rho, \tilde{\rho})\right\},$$

where

$$\begin{aligned} \Psi(\rho, \tilde{\rho}) &= \Phi(\rho) - \Phi(\tilde{\rho}) - \partial_{\frac{1}{\rho}}\Phi(\tilde{\rho}) \left(\frac{1}{\rho} - \frac{1}{\tilde{\rho}}\right) \\ &= \int_{\tilde{\rho}}^{\rho} \frac{p(\zeta) - p(\tilde{\rho})}{\zeta^2} d\zeta. \end{aligned}$$

As shown in [4],  $\rho\Psi(\rho, \tilde{\rho})$  is equivalent to  $|\rho - \tilde{\rho}|^2$  for suitably small  $|\rho - \tilde{\rho}|$ , and hence, there are positive constants  $c_0$  and  $c_1$  such that

$$(3.3) \quad c_0^{-1}|U| \leq \rho\tilde{\mathcal{E}} \leq c_0|U|,$$

where  $U = (\phi, \psi)$ ,  $\phi = \rho - \tilde{\rho}$  with  $|\phi| \leq c_1$ .

Since  $H^s \hookrightarrow L^\infty$  we can find a number  $M > 0$  such that if  $E_s(t) \leq M$ , then  $\|\phi(t)\|_\infty \leq c_1$  and  $\inf_x \phi(x, t) \geq -\frac{1}{4} \inf_{x_1} \tilde{\rho}(x_1)$  for all  $t \in [0, T]$ .

A direct calculation shows

$$\begin{aligned} \partial_t(\rho\mathcal{E}) + \operatorname{div}(\rho u\mathcal{E} + (p(\rho) - p(\tilde{\rho}))\psi) &= \mu \operatorname{div}\left(\frac{1}{2}|\nabla\psi|^2\right) + (\mu + \mu') \operatorname{div}(\psi \operatorname{div}\psi) \\ &\quad - \mu|\nabla\psi|^2 - (\mu + \mu')(\operatorname{div}\psi)^2 + \mathcal{R}_0, \end{aligned}$$

where  $\mathcal{R}_0 = \mathcal{R}_0(x, t)$  is the function defined by

$$\mathcal{R}_0 = -\rho(\psi \cdot \nabla \tilde{u}) \cdot \psi - (p(\rho) - p(\tilde{\rho}) - p'(\tilde{\rho})\phi) \operatorname{div} \tilde{u} - \frac{1}{\tilde{\rho}} \phi \psi \cdot L\tilde{u}.$$

Proposition 3.3 now follows from this identity and (3.3). This completes the proof.

To estimate higher order derivatives, we rewrite (3.1) as

$$\begin{aligned} (3.4) \quad &\partial_t \phi + u \cdot \nabla \phi + \rho_+ \operatorname{div} \psi = f, \\ &\partial_t \psi + \frac{1}{\rho_+} L\psi + \frac{p'(\rho_+)}{\rho_+} \nabla \phi = g, \\ &\psi|_{x_1=0} = 0, \\ &(\phi, \psi) \rightarrow (0, 0) \quad (x_1 \rightarrow \infty), \\ &(\phi, \psi)|_{t=0} = (\phi_0, \psi_0) \end{aligned}$$

where  $L\psi = -\mu\Delta\psi - (\mu + \mu')\nabla \operatorname{div}\psi$ ,  $f = \hat{f} + \tilde{f}$  and  $g = -\tilde{u} \cdot \nabla\psi + \hat{g} + \tilde{g}$ . Here  $\hat{f} = -\phi \operatorname{div}\psi$ ,  $\tilde{f} = -(\tilde{\rho} - \rho_+) \operatorname{div}\psi - \psi \cdot \nabla \tilde{\rho} - \phi \operatorname{div} \tilde{u}$ , and  $\hat{g} = \hat{g}^{(1)} + \hat{g}^{(2)} + \hat{g}^{(3)}$ ,  $\tilde{g} = \tilde{g}^{(1)} + \tilde{g}^{(2)} + \tilde{g}^{(3)}$  with

$$\begin{aligned} \hat{g}^{(1)} &= \hat{P}(\rho, \rho_+) \phi \nabla \phi, \quad \hat{g}^{(2)} = \frac{1}{\rho \rho_+} \phi L\psi, \quad \hat{g}^{(3)} = -\psi \cdot \nabla \psi, \\ \tilde{g}^{(1)} &= \hat{P}(\rho, \rho_+) (\tilde{\rho} - \rho_+) \nabla \phi + \hat{P}(\rho, \tilde{\rho}) \phi \nabla \tilde{\rho}, \\ \tilde{g}^{(2)} &= \frac{1}{\rho \tilde{\rho}} (L\tilde{u}) \phi + \frac{1}{\rho \rho_+} (\tilde{\rho} - \rho_+) L\psi, \\ \tilde{g}^{(3)} &= -\psi \cdot \nabla \tilde{u}, \end{aligned}$$

$$P(\rho_1, \rho_2) = \int_0^1 p''(\rho_2 + \theta(\rho_1 - \rho_2)) d\theta, \quad \hat{P}(\rho_1, \rho_2) = \frac{p'(\rho_1)}{\rho_1 \rho_2} - \frac{P(\rho_1, \rho_2)}{\rho_2}.$$



Before proceeding further, we introduce some notations. We define  $N_\sigma \geq 0$  by

$$\begin{aligned} N_\sigma(t)^2 &= \int_0^t \|\widehat{f}\|_\sigma^2 + \|\widehat{g}\|_{\sigma-1}^2 + \|\psi \cdot \nabla \phi\|_{\sigma-1}^2 d\tau \\ &\quad + \sum_{1 \leq 2j+|\alpha'| \leq \sigma} \int_0^t |(\partial_\tau^j \partial_{x'}^{\alpha'} \widehat{g}, \partial_\tau^j \partial_{x'}^{\alpha'} \psi)| d\tau \\ &\quad + \sum_{1 \leq 2j+|\alpha| \leq \sigma} \int_0^t |(\operatorname{div} \psi, |\partial_\tau^j \partial_x^\alpha \phi|^2)| d\tau \\ &\quad + \sum_{2j+|\alpha| \leq \sigma} \int_0^t \|[\partial_\tau^j \partial_x^\alpha, \psi \cdot \nabla] \phi\|_2^2 d\tau, \end{aligned}$$

where  $[C, D]$  denotes the commutator of  $C$  and  $D$

$$[C, D] = CD - DC.$$

We also define  $R_\sigma \geq 0$  ( $\sigma \geq 1$ ) by

$$\begin{aligned} R_\sigma(t)^2 &= R_{\sigma-1}(t)^2 + \int_0^t \|\widetilde{f}\|_\sigma^2 + \|\widetilde{g}\|_{\sigma-1}^2 + \|\widetilde{u} \cdot \nabla \phi\|_{\sigma-1}^2 d\tau \\ &\quad + \sum_{1 \leq 2j+|\alpha'| \leq \sigma} \int_0^t |(\partial_\tau^j \partial_{x'}^{\alpha'} \widetilde{g}, \partial_\tau^j \partial_{x'}^{\alpha'} \psi)| d\tau \\ &\quad + \sum_{1 \leq 2j+|\alpha| \leq \sigma} \int_0^t |(\operatorname{div} \widetilde{u}, |\partial_\tau^j \partial_x^\alpha \phi|^2)| d\tau \\ &\quad + \sum_{2j+|\alpha|+\ell \leq \sigma-1} \int_0^t \|[\partial_\tau^j \partial_x^\alpha \partial_{x_1}^{\ell+1}, \widetilde{u} \cdot \nabla] \phi\|_2^2 d\tau, \end{aligned}$$

**Proposition 3.4.** *Let  $1 \leq \sigma \leq s$ . Assume that (3.2) holds. Then there exists a constant  $C > 0$  such that*

$$E_\sigma(t)^2 + D_\sigma(t)^2 \leq C\{\|U_0\|_{H^s}^2 + R_\sigma(t)^2 + N_\sigma(t)^2\}.$$

To prove Proposition 3.4 we introduce a notation

$$|v|_k = \left( \sum_{|\alpha|=k} \|\partial_x^\alpha v\|_2^2 \right)^{1/2}.$$

We also define  $T_{j,\alpha'}$  by

$$T_{j,\alpha'} v = \partial_t^j \partial_{x'}^{\alpha'} v.$$

Proposition 3.4 follows from the following inequalities.

**Proposition 3.5.** *Let  $\sigma$  be a nonnegative integer satisfying  $\sigma \leq s$ .*

(i) *Let  $j$  and  $\alpha'$  satisfy  $2j + |\alpha'| = \sigma$ . Then*

$$\|T_{j,\alpha'} U(t)\|_2^2 + \int_0^t \|L^{1/2} T_{j,\alpha'} \psi\|_2^2 d\tau \leq C\{\|U_0\|_{H^s}^2 + R_\sigma(t)^2 + N_\sigma(t^2)\},$$

where  $\|L^{1/2} \psi\|_2^2 = \mu \|\nabla \psi\|_2^2 + (\mu + \mu') \|\operatorname{div} \psi\|_2^2$ .

(ii) *Let  $j$  and  $\alpha'$  satisfy  $2j + |\alpha'| = \sigma - 1$ . Then*

$$\|L^{1/2} T_{j,\alpha'} \psi(t)\|_2^2 + \int_0^t \|T_{j+1,\alpha'} \psi\|_2^2 d\tau \leq \eta D_\sigma(t)^2 + C_\eta \mathcal{N}_\sigma(t)^2$$

for any  $\eta > 0$ . Here and in what follows  $\mathcal{N}_\sigma(t)^2$  denotes

$$\mathcal{N}_\sigma(t)^2 = \|U_0\|_{H^s}^2 + E_{\sigma-1}(t)^2 + D_{\sigma-1}(t)^2 + R_\sigma(t)^2 + N_\sigma(t^2).$$

(iii) *Let  $j$  and  $\alpha'$  satisfy  $2j + |\alpha'| + \ell = \sigma - 1$ . Then*

$$\begin{aligned} & \|T_{j,\alpha'} \partial_{x_1}^{\ell+1} \phi(t)\|_2^2 + \int_0^t \|T_{j,\alpha'} \partial_{x_1}^{\ell+1} \phi\|_2^2 d\tau \\ & \leq \eta D_\sigma(t)^2 + C_\eta \{\mathcal{N}_\sigma(t)^2 + \int_0^t \|T_{j+1,\alpha'} \partial_{x_1}^\ell \psi\|_2^2 + \|\partial_x \partial_{x'} T_{j,\alpha'} \partial_{x_1}^\ell \psi\|_2^2 d\tau\} \end{aligned}$$

for any  $\eta > 0$ .

(iv) *Let  $j$  and  $\alpha'$  satisfy  $2j + |\alpha'| + \ell = \sigma - 1$  and set  $\frac{D\phi}{Dt} = \partial_t \phi + u \cdot \nabla \phi$ .*

*Then*

$$\int_0^t |T_{j,\alpha'} \frac{D\phi}{Dt}|_{\ell+1}^2 d\tau \leq \eta D_\sigma(t)^2 + C_\eta \{\mathcal{N}_\sigma(t)^2 + \int_0^t \|T_{j+1,\alpha'} \partial_{x_1}^\ell \psi\|_2^2 + \|\partial_x \partial_{x'} T_{j,\alpha'} \partial_{x_1}^\ell \psi\|_2^2 d\tau\}$$

for any  $\eta > 0$ .

(v) *Let  $j$  and  $\alpha'$  satisfy  $2j + |\alpha'| + \ell = \sigma - 1$ . Then*

$$\begin{aligned} \int_0^t |T_{j,\alpha'} \psi|_{\ell+2}^2 + |T_{j,\alpha'} \phi|_{\ell+1}^2 d\tau & \leq C \int_0^t \{|T_{j+1,\alpha'} \psi|_\ell^2 + |T_{j,\alpha'} f|_{\ell+1}^2 + |T_{j,\alpha'} \frac{D\phi}{Dt}|_{\ell+1}^2 \\ & \quad + |T_{j,\alpha'} (\tilde{u} \cdot \nabla \psi)|_\ell^2 + |T_{j,\alpha'} \widehat{g}|_\ell^2 + |T_{j,\alpha'} \widetilde{g}|_\ell^2\} d\tau. \end{aligned}$$

(vi) *Let  $j$  and  $\alpha'$  satisfy  $2j + 1 \leq \sigma$ . Then*

$$\|\partial_t^{j+1} \phi(t)\|_2^2 + \int_0^t \|\partial_\tau^{j+1} \phi\|_2^2 d\tau \leq \eta D_\sigma(t)^2 + C_\eta \mathcal{N}_\sigma(t)^2$$

for any  $\eta > 0$ .

**Proof.** Proposition 3.5 can be proved by the energy method as in [1, 6]. The details can be found in [3].

It remains to estimate  $R_\sigma$  and  $N_\sigma$ . To estimate  $R_0$  we will use a special case of Hardy's inequality

$$(3.5) \quad \left\| \frac{1}{x_1} \int_0^{x_1} v(y) dy \right\|_{L^2(0,\infty)} \leq C \|v\|_{L^2(0,\infty)}.$$

In a similar manner as in [1, 4], applying (3.5) and the decay estimates in Proposition 2.1 together with the Gagliardo-Nirenberg inequality, one can show that

$$R_0(t)^2 \leq C\{\delta D_0(t)^2 + E_s(t)D_s(t)^2\}.$$

Here we note that we also use the monotonicity of  $\tilde{u}^1(x_1)$  when  $M_+ = 1$ .

For  $\sigma \geq 1$ , one can show, as in [1], that

$$R_\sigma(t)^2 + N_\sigma(t)^2 \leq C\{D_{\sigma-1}(t)^2 + \delta D_\sigma(t)^2 + E_s(t)D_s(t)^2\},$$

provided that  $E_s(t) < \min\{M, 1\}$ . Therefore, it follows that if  $\delta$  is sufficiently small and  $E_s(t) < \min\{M, 1\}$  then

$$E_s(t)^2 + D_s(t)^2 \leq C\{\|U_0\|_{H^s}^2 + E_s(t)D_s(t)^2\},$$

and hence, we conclude that

$$E_s(t)^2 + D_s(t)^2 \leq C\|U_0\|_{H^s}^2,$$

provided that  $\|U_0\|_{H^s}$  is sufficiently small. This completes the proof of Proposition 3.2.

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